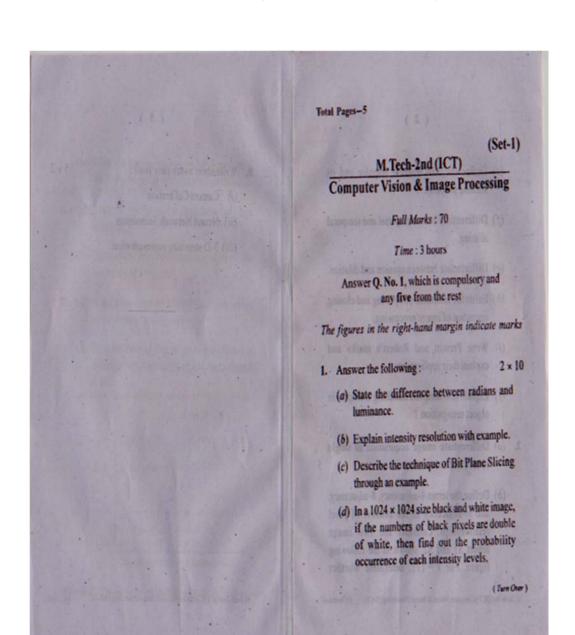
VEER SURENDRA SAI UNIVERSITY OF TECHNOLOGY, BURLA DEPARTMENT OF COMPUTER SCIENCE AND ENGINEERING & INFORMATION TECHNOLOGY

SESSION 2014-2015 (EVEN SEMESTER)



(3)

the two points 'p' and 'q' are (i) 4-adjacent,

(e) Define the unit discrete impulse and its shifting property.

(2)

- (f) Differentiate between spatial and temporal aliasing.
- (g) Differentiate between erosion and dilation.
- (h) Enlist the functions of opening and closing operation of image processing.
- (i) Write Prewitt and Robert's masks and explain their applications.
- (j) Explain how template matching is helpful in object recognition?
- (a) Differentiate image acquisition in single sensor and sensor stripes.
 5
 - (b) Define the terms 4-adjacency, 8-adjacency, and m-adjacency in the context of pixel relationships. Consider the two image subset S1 and S2, shown in the following figure. For V= {1}, determine whether

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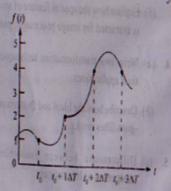
(ii) 8-adjacent, or (iii) m-adjacent.									,
121	S				S ₂				
0	0	0	0	0	0	0	1	1	0
1	0	0	1	0	0	1	0	0	1
1	0	0	1	0	0	1	0	0	0
0	0	1	1	0	0	0	0	0	0
					0				_

- 3. (a) Describe different methods of classification. 5
 - (b) Explain how the spatial feature of an object is extracted for image processing purpose. 5
- (a) Write two transformation techniques with their applications.
 - (b) Describe how the Ideal and Butterworth low -pass filter works.
- (a) Differentiate between smoothing and sharpening of linear filters.

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(5)

- (b) What do you mean by unsharp masking? Write the steps to perform the operation. 5
- 6. (a) Explain different techniques of age detection.
 - (b) List out the Moore Technique to track the boundary of a region.
- 7. (a) What do you mean by MPP? Write the steps to implement the algorithm.
 - (b) Find the Fourier Transform of the following figure where the values of x varies between 0 to 3.



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8. Write short notes (any two):

5×2

- (i) Camera Calibration
- (ii) Neural Network Techniques
- (iii) 3-D structure representation.

M.Tech-2nd (ICT) Computer Vision & Image Processing (Sci-1)

BE-160